PRESIDENCY UNIVERSITY BENGALURU

SET A

# SCHOOL OF ENGINEERING END TERM EXAMINATION - JAN 2024

Semester : Semester III 2022 Course Code : CSE2066 Course Name : Computer Graphics Program : B.Tech. Date : 08-JAN-2024 Time : 9:30AM - 12:30 PM Max Marks : 100 Weightage : 50%

### Instructions:

- (i) Read all questions carefully and answer accordingly.
- (ii) Question paper consists of 3 parts.
- (iii) Scientific and non-programmable calculator are permitted.

(iv) Do not write any information on the question paper other than Roll Number.

#### PART A

### ANSWER ALL THE QUESTIONS

- **1.** How the Bresenham's line drawing algorithm overcomes the drawbacks of DDA?
- **2.** Write the rotation matrix to rotate a point P(x,y) with an angle 'theta' to P'(x',y') and represent P'(x',y') in terms of P(x,y)
  - (CO2) [Knowledge]

(CO3) [Knowledge]

(CO3) [Knowledge]

(CO4) [Knowledge]

(CO1) [Knowledge]

- **3.** Outline the advantages and disadvantages of Cohen-Sutherland line clipping algorithm.
- 4. What is quadric surfaces?
- 5. Define 2D Curves and 3D Space Curves

### PART B

### **ANSWER ALL THE QUESTIONS**

### 5 X 10M = 50M

 $5 \times 2M = 10M$ 

6. Explain general three dimensional transformation pipeline from world coordinates to device coordinates with all the steps involved.

(CO1) [Comprehension]



**7.** Explain Two Dimensional viewing pipeline architecture to map world-coordinate scene description to device coordinates with a neat diagram.

(CO2) [Comprehension]

8. Explain perspective projection with a neat diagram and summarize the perspective projection types in detail.

(CO3) [Comprehension]

**9.** Distinguish between parametric and non-parametric representation for plane curves and surfaces with suitable examples and diagrams.

(CO4) [Comprehension]

**10.** Explain Bezier and Spline curves for curve representations in computer graphics with suitable diagrams.

(CO4) [Comprehension]

## PART C

## ANSWER ALL THE QUESTIONS

2 X 20M = 40M

- **11.** A) Demonstrate 3D Transformations in detail with proper examples and diagrams that include change in Size, Shape, Position and Orientation of any object.
  - B) Derive the Three Dimensional Transformation matrix for Translation, Rotation and Scaling.

(CO3) [Application]

A) Illustrate Cohen-Sutherland line clipping algorithm and explain the working in detail.
B) Apply Cohen-Sutherland algorithm to clip a line with end points P1(10,30) and P2(80,90), Let ABCD be the rectangular clip window with A(20,20), B(90,20),C(90,70) and D(20,70).Find the region code for the end points of the line.

(CO4) [Application]